# Barycentric Coordinate and its Applications 

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## Overview

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## Introduction:

To understand Barycentric Coordinate, we need to introduce some basic terms and theorems.

- Archimedes' law of lever tells us that "two magnitudes balance at distances reciprocally proportional to their magnitudes" [2]

[1]
- If we denote the three vertices of a 2D triangle as $A=\left(x_{a}, y_{a}\right)$, $B=\left(x_{b}, y_{b}\right), C=\left(x_{c}, y_{c}\right)$, then the edge AB can be defined as $B-A$, and edge $A C$ as $C-A$.


## Definition:

Let's first consider the Barycenter P on a real line.

[1]

- with the mass on $A$ as $m_{A}$ and on $B$ as $m_{B}$. Following the Archimedes' Law of the lever, we have $m_{A}\left(x_{P}-x_{A}\right)=m_{B}\left(x_{B}-x_{P}\right)$.
- By solving the equation, we get $x_{P}=w_{A} x_{A}+w_{B} x_{B}$ where $w_{A}=\frac{m_{A}}{m_{A}+m_{B}}$ and $w_{B}=\frac{m_{B}}{m_{A}+m_{B}}$
- Here, $x_{P}$ is our Barycenter $P$


## Definition:

Now, let's move the idea to triangle with vertices $A, B, C$

- We can write the Barycentric Coordinate P as a polynomial about $A, B, C$ with coefficients $\beta$ and $\gamma$.
- $\begin{aligned} p & =A+\beta(B-A)+\gamma(C-A)=A+\beta B-\beta A+\gamma C-\gamma A \\ & =(1-\beta-\gamma) A+\beta B+\gamma C\end{aligned}$
- Therefore, the Barycentric Coordinate $P$ is defined as:

$$
P=\alpha A+\beta B+\gamma C
$$

where $\alpha+\beta+\gamma=1$

## Properties:

There are some interesting properties about the Barycentric Coordinate $P$ of a triangle.

- A point $P$ is inside the $A B C$ triangle if and only if:

$$
\begin{aligned}
& 0<\alpha<1 \\
& 0<\beta<1 \\
& 0<\gamma<1
\end{aligned}
$$

- By changing the values of $\alpha, \beta, \gamma$ between 0 and 1 , the point $P$ will move smoothly inside the triangle.
- The values of $\alpha, \beta, \gamma$ corresponds to the quotient of the areas of triangles $A B P, A C P, B C P$ to the area of whole triangle $A B C$ :

$$
\begin{aligned}
\alpha & =S_{B P C} / S_{A B C} \\
\beta & =S_{A P C} / S_{A B C} \\
\gamma & =S_{A P B} / S_{A B C}
\end{aligned}
$$

## Applications:

- The most common application of Barycentric Coordinate is shading the triangle with RGB coloring.

[1]
- Take the green coloring for example. We set the weight of the right corner vertex to 256 , and the rest two vertices to 0 . When we toggle the values of $\alpha, \beta, \gamma$, the color will change as the coordinates of $P$ change.
- One innovative use of Barycentric Coordinates is applying it on the deformation of the graph objects. The method uses the LBC (Local Barycentric Coordinates)[3].
- We first define $c_{1}, c_{2}, \ldots, c_{n}$ to be the control points which are the vertices of a closed control cage. And let $\mathbb{S}$ be the domain bounded by the cage. The goal is to find a function $w_{i}: \mathbb{S} \mapsto \mathbb{R}$ for each $c_{i}$, such that $\left[w_{1}(x), \ldots, w_{n}(x)\right]$ is a set of generalized barycentric coordinates of $x \in \mathbb{S}$ with respect to the control points $\left\{c_{i}\right\}$.
- These coordinate functions are used for interpolating function values $f\left(c_{1}\right) \ldots, f\left(c_{n}\right)$ defined as $f(x)=\sum_{i=1}^{n} w_{i}(x) f\left(c_{i}\right)$ which is used for shape deformation.
- The most important thing about LBC is that it fulfills the locality: a control point only influences its nearby regions, and a point $x \in \mathbb{S}$ is influenced by a small number of control points.
- To calculate LBC, we aim to minimize a target function based on Total Variation. So we can write it out as a convex optimization problem[3]:

$$
\begin{aligned}
\min _{w_{1}, \ldots, w_{n}} & \sum_{i=1}^{n} \int_{\Omega}\left|\nabla w_{i}\right| \\
\text { s.t. } & \sum_{i=1}^{n} w_{i}(x) c_{i}=x, \sum_{i=1}^{n} w_{i}=1, w_{i} \geq 0, \forall x \in \Omega \\
& w_{i}\left(c_{j}\right)=\delta_{i j} \forall i, j
\end{aligned}
$$

## Results:

- The results of image deformation are shown below:



## Reference

P. LidBerg, Barycentric and wachspress coordinates in two dimensions: Theory and implementation for shape transformations, 2011.

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## Thank You

